



WIDE-AREA CONTROL OF NEW YORK STATE POWER GRID WITH MULTI- FUNCTIONAL MULTI-BAND POWER SYSTEM STABILIZERS

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Outline

- Project description
- Controller design
- Results
- Conclusions





Project description

- Application of methodology and technologies developed by Hydro-Québec to NYS system
- Objectives : Dynamic behavior improvement of New York State Grid
 - frequency response
 - oscillation damping
- Solution
 - Using FACTS devices
 - Both objectives do not interfere or conflict – separate tuning
 - Local and/or Wide-area control
 - Enabling technology: Multi-Functional Multi-Band Power System Stabilizer (MF-MBPSS)
 - Capable of processing remote signals



Controller design methodology

- Sensitivity analysis
- Simulation-based metrics
- System identification methods for linear model development
 - Low order models built from simulation data
 - Pulse probing of reference signals
 - Recorded response used to reconstruct low order state space model
 - Useful for linear analysis and controller model-based design
 - Modal analysis
 - Control loop signal selection
 - Controller setting



Controller design for primary frequency control

- Utilization of load voltage sensitivity
- Siting determined by sensitivity analysis
 - Large plants and FACTS devices
- Average PMU frequency used as input
 - Actual 24 PMUs installed in NYS
- Using just low band is sufficient
- Controller performance
 - Large disturbances – nonlinear simulations
- Conclusion:
 - 3 plants and one SVC



Controller design for oscillation damping

- Control loop signal selection based on
 - Observability/controllability and modal analysis
 - Available PMU signals on NYS
- Conclusion
 - STATCOM in NYS grid found to be best
 - Local signal (STATCOM bus frequency deviation) performs best compared to considered remote signals from PMUs installed to NYS



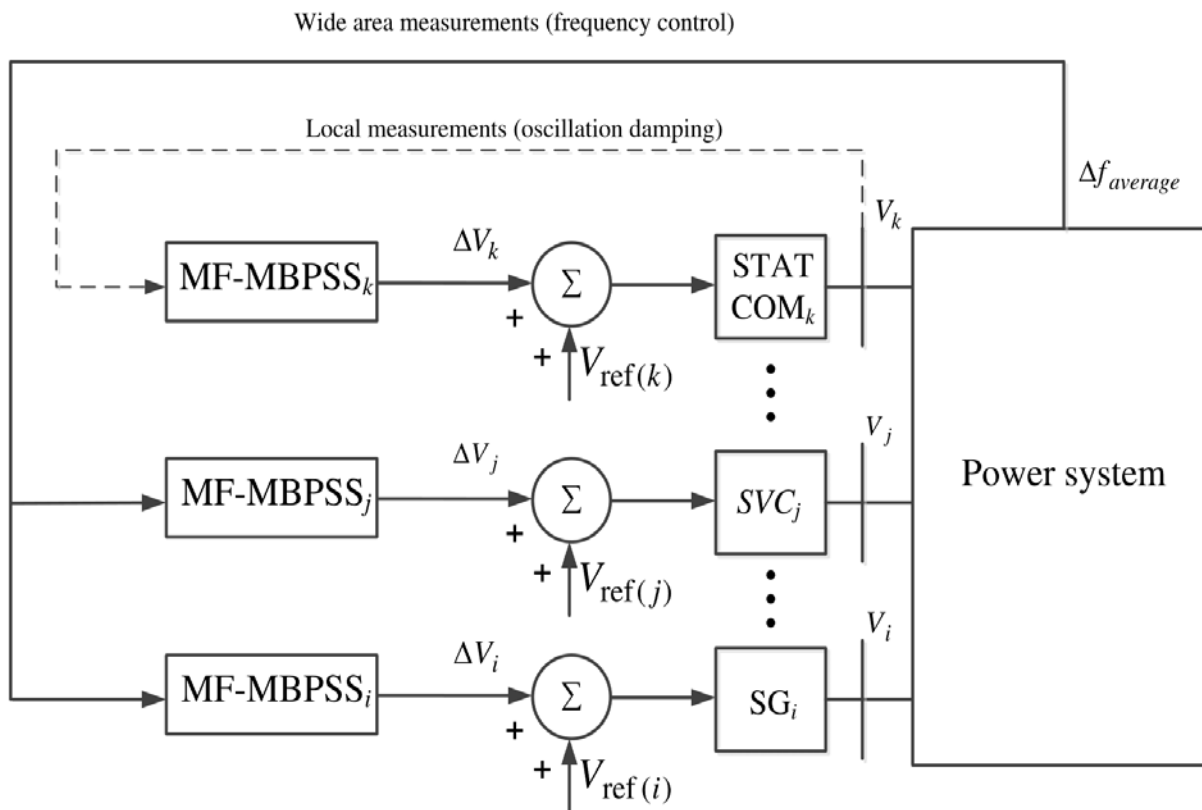
Controller design for oscillation damping

- Controller tuning
 - Model-based design
 - Nonlinear constrained optimization
 - Objective function
 - Function of the area under the envelopes of oscillatory modes
 - Constraints
 - Minimum damping
 - Robustness metrics
 - Limits on MF-MBPSS parameters
- Controller performance
 - Testing with small-signal and large disturbances – nonlinear simulations



Results : control strategy for oscillation damping and frequency response improvement

- Frequency control: 3 plants and 1 SVC
- Oscillation damping: STATCOM





Results

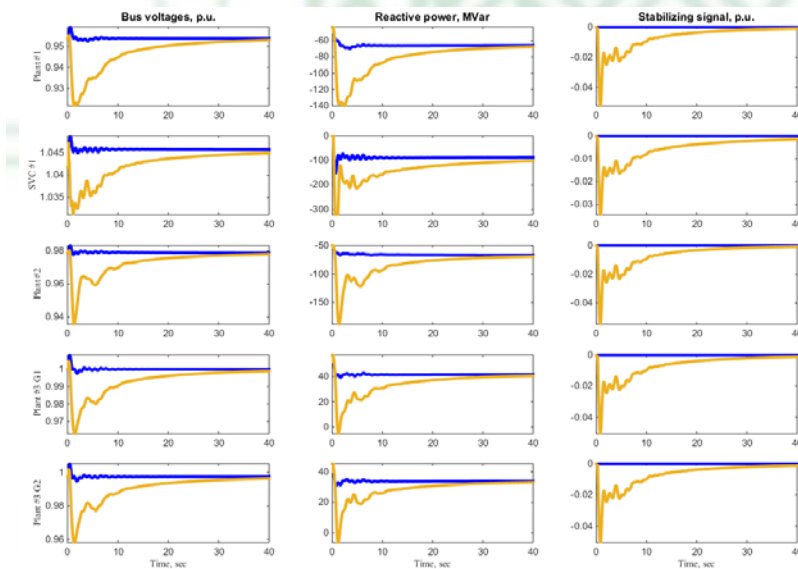
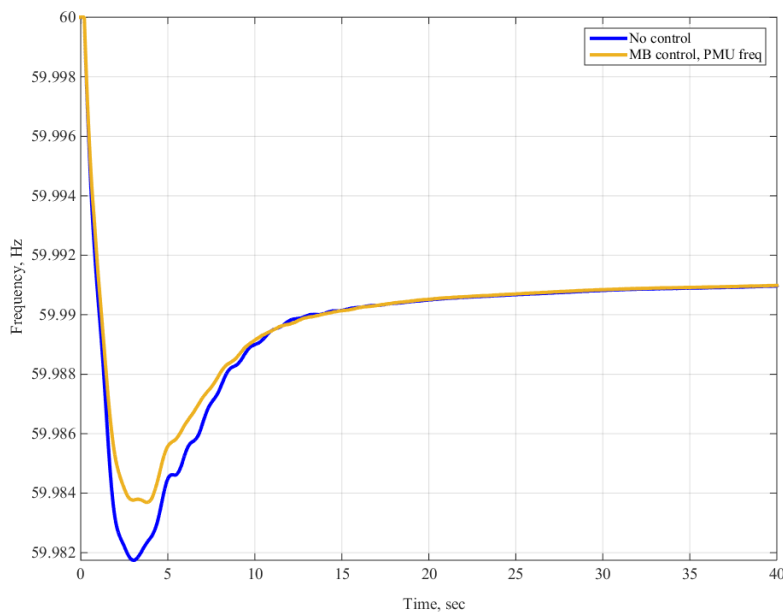
- Controller settings (simplified tuning) : band central gain (G) and central frequency (F) values

Device	Objective	R	Low		Intermediate		High	
			F	G	F	G	F	G
Plant #1	Frequency	0.01	0.08	92	-	-	-	-
SVC #1	Frequency	0.01	0.061	65	-	-	-	-
Plant #2	Frequency	0.01	0.085	95	-	-	-	-
Plant #3	Frequency	0.01	0.075	90	-	-	-	-
STATCOM	Damping	1.2	0.0457	120	0.8871	180	1.736	280



Results

- Impact on frequency : Contingency: loss of ~ 1GW



- Frequency metrics

Control	Min frequency	Nadir-Based Frequency Response (NBFR)		
	Hz	MW/0.1Hz	MW gain	Gain, %
No control	59.982	5586.3	667.78	11.95
MF-MBPSS	59.984	6254.1		



Results

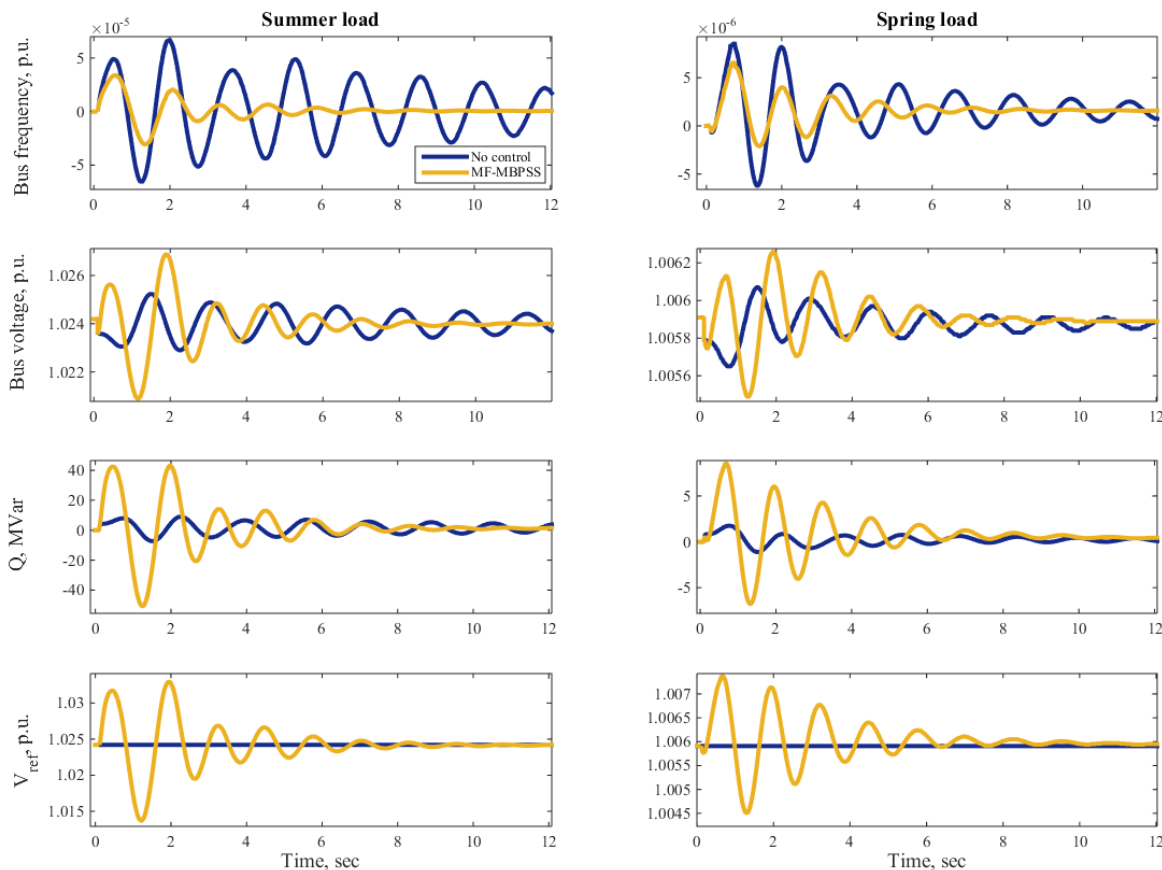
- Oscillatory stability: linear analysis, different load scenarios

Case	Inter-area mode #	Frequency, Hz		Damping ratio	
		Open-loop	Closed-loop	Open-loop	Closed-loop
Spring	1	0.979	0.951	0.0572	0.089
	2	0.804	0.823	0.0788	0.198
Summer	1	0.9506	0.913	0.0863	0.143
	2	0.754	0.812	0.1145	0.314



Results

- Large disturbance test, different load scenarios





Conclusions

- Observable impact on frequency response can be achieved with limited reactive power
- System-wide damping improvement with little modulation
- Developed tuning procedures and methodologies useful for very large systems

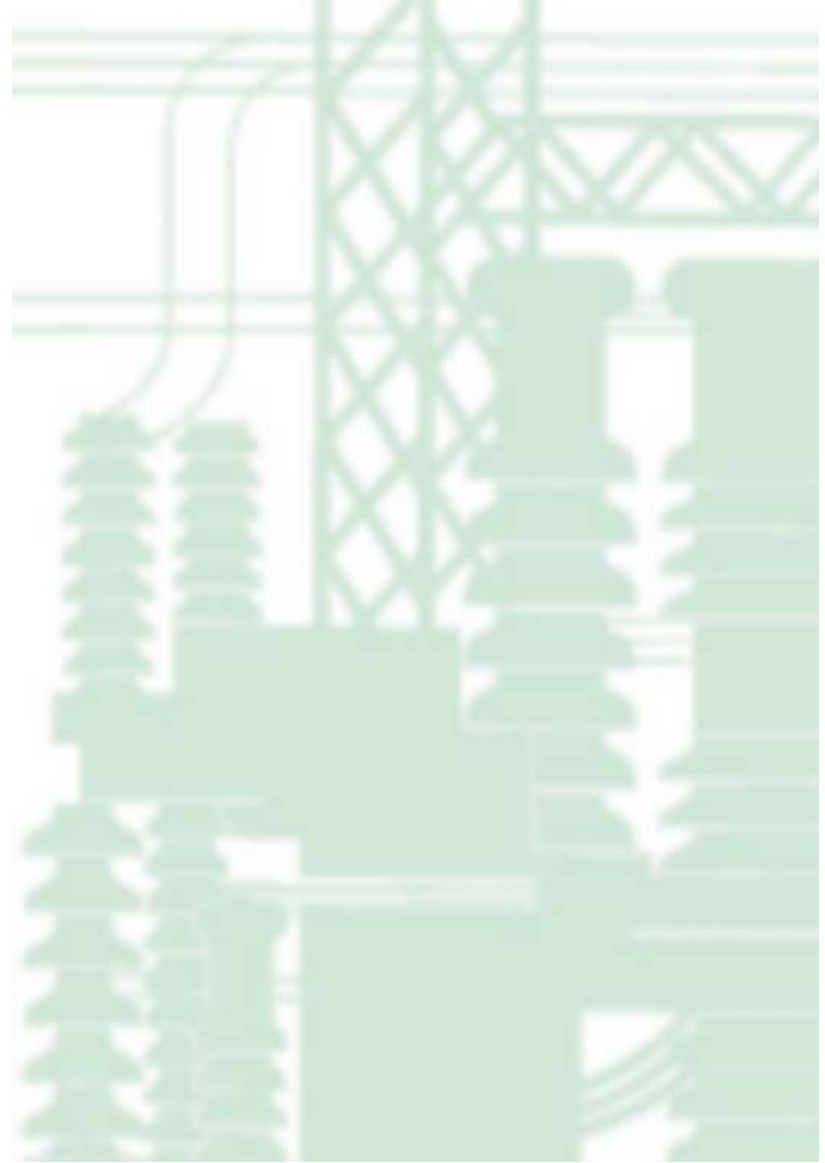




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THANK YOU!

- QUESTIONS?





Controller topology

